

SMART IRRIGATION SYSTEM USING IOT

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Abstract:- In India, agriculture plays an important role for development in food production. In our country, agriculture depends on the monsoons which are not sufficient source of water. So the irrigation is used in agriculture field. Internet of Things (IoT) is a milestone in the evolution of technology. IOT plays an important role in many fields, one of that is Agriculture by which it can feed billions of people on Earth in future. The target of this paper is expecting to conquer this test, the entire framework is miniature control based and can be worked from far off area through remote transmission so there is no compelling reason to worry about water system timing according to trim or soil condition. Sensor is utilized to take sensor perusing of soil like soil dampness, temperature, air dampness and dynamic is constrained by client (rancher) by utilizing microcontroller. The information got from sensors are shipped off worker data set utilizing remote transmission. The irrigation will be mechanized when the dampness and temperature of the field is diminished. The rancher is advised with the data in regards to field condition through portable intermittently. This framework will be more valuable in regions where there is shortage of water and will be worth efficient with fulfilling its prerequisites.

Term Index:- LOT,MC

I. INTRODUCTION

In India, where 60-70% economy depends on agriculture, there is a great need to modernize the conventional agricultural practices for the better productivity. Due to unplanned use of water the ground water level is decreasing day by day, lack of rains and scarcity of landwater also results in decrement in volume of water on earth. These days, water lack is getting one of the biggest issues on the planet. We need water in each and every field. In our everyday life additionally water is essential. Agriculture is one of fields where water is required in tremendous amount. Wastage of water is the major problem in agribusiness [7]. Each time overabundance of water is given to the fields. There are numerous methods to save or to control wastage of water in agribusiness.

The goal of the framework incorporates moderate energy and water assets, handles the framework physically and automatically, distinguishes the degree of water. Due to the climatic changes and absence of exactness; farming has resulted in helpless yield when contrasted with populace growth. Irrigation is generally done utilizing trench frameworks in which water is siphoned into fields after ordinary time span any criticism of water level in field. This sort of irrigation influences crop wellbeing and produces a poor yield because a few harvests are too touchy to even consider watering content in soil.

For effective and optimum utilization of fresh water irrigation, it becomes essential to develop the smart irrigation systems based on dynamic prediction of soil moisture pattern of the field and precipitation information of upcoming days. This paper presents an intelligent system that predicts soil moisture based on the information collected from the sensors deployed at the field and the weather forecast information available on the Internet. The field data has been collected through a self designed sensor node.

II. COMPARATIVE STUDY

Table 1 illustrates the overall view and comparisons of various agricultural system techniques used.

TABLE 1
Comparisons of various Smart Agricultural Systems

Existing System	Technologies used	Advantages	Cloud Implementation	Data Acquisition
Smart Irrigation System	MATLAB, wireless sensor, IOT.	Optimizes the water usage, provides a remote controlling, monitor the system.	✓	✓
Non-Linear Analysis of Soil Microwave Heating	Microwave antennas, electromagnet ethic heating.	Allows a very effective solution.	✗	✓
Cucumber Disease Detection	Artificial neural network, MATLAB.	Provides the Accuracy	✗	✓
Identifying and Monitoring Winter Wheat Diseases		Diseases could be determined and Differentiated.	✗	✓
Detection and Identification of Disease Stages [15]	ASD spectro radiometer, MATLAB.		✗	✓
Mega-Nano Detection of Foodborne Pathogens and Transgenes [16]	Quantum dots, DNA.	Established an on-the-plant design for detecting signature molecules.	✗	✓
Robotic Disease Detection in Green Houses [18]	RGB camera, laser sensor, computer automation.	Overcome the threat in the crops or leaves in the agriculture.	✗	✓
Identification and Classification of Fungal Disease [19]	Image processing, pattern recognition.	Monitor the crop for possible diseases and avoids upcoming loss of crops.	✗	✓

III. LITERATURE SURVEY

5.1. Automated Irrigation System using WSN and GPRS Module

Automated Irrigation system using WSN and GPRS Module having main goal is that optimize use of water for agriculture crops [1]. This system is composed of distributed wireless sensor network with soil moisture and temperature sensor in WSN. Gateway units are used to transfer data from sensor unit to base station, send command to actuator for irrigation control and manage data of sensor unit. Algorithm used in system for controlling water quantity as per requirement and condition of field. It is programmed in microcontroller and it sends command through actuator to control water quantity through valve unit. Whole system is powered by photovoltaic panels. Communication is duplex take place through cellular network. Web

application manage the irrigation through continuous monitoring and irrigation scheduling programming. It can be done through web pages.

5.2. Crop Monitoring System based on WSN

The subsequent section introduces the Bluetooth technology. Wireless Sensor network crop monitoring application is useful to farmer for precision agriculture. The application monitors the whole farm from remote location using Internet Of Things (IOT). Application works on sensor network and two types of nodes. Energy saving algorithm is used in node to save energy. Tree based protocol is used for data collection from node to base station. System having two nodes one node that collect all environmental and soil parameter value and the other consist of camera to capture images and monitor crops. In this System Environmental changes are not considered for sensor reading. System user is not able to program application. There is no controlling system for application.

5.3. Automatic Drip Irrigation System using WSN and Data Mining Algorithm

Data mining algorithm are used to take decisions on drip irrigation system. Automated drip irrigation system having WSN placed in all over farm and different type of sensors. [9] WSN uses ad hoc network which gives self configuration and flexibility. Sensor data is given to base station and data is received using zigbee. Data processing is done at base station for decision making. Data mining algorithm is used to take decision on data from sensor to drip.

All observation are remotely monitor through web application. This system works on Naïve Bayes algorithm for irrigation control. Algorithm works on previous data set for decision making if any attribute is not frequent result is zero [11].

IV. COMPONENTS

4.1. Arduino Microcontroller

Arduino is an open-source electronics platform based on easy-to use hardware and software [5][4]. Arduino boards are able to read inputs – light on a sensor, a finger on a button – and turn it into an output – activating a motor, turning on an LED. A microcontroller is a small computer on a single integrated circuit. In modern terminology, it is a system on a chip. It contains one or more CPUs along with memory and programmable input / output peripherals. Microcontrollers are designed for embedded application. They are used in automatically controlled products and devices, such as automobile engine control systems, implantable medical devices, remote controls, office machines and other embedded systems [4].



Fig. 1: Arduino Microcontroller

Fig.1 shows Arduino microcontroller where the Arduino board can communicate at various baud rates. A baud is a measure of how many times the hardware can send 0's and 1's in a second. The software used by the Arduino is Arduino IDE.

4.2. Sensors

In this system two sensors are used in order to obtain the data about the soil and environmental condition, soil moisture sensor and temperature and humidity sensor.

4.2.1. Soil Moisture Sensor

Soil moisture sensors measure the volumetric water content in soil [11]. Since the direct gravimetric measurement of free soil moisture requires removing, drying and weighing of a sample, soil moisture sensors measure the volumetric water content indirectly by using some other property of the soil, such as electrical resistance, dielectric constant, or interaction with neutrons, as a proxy for the moisture content. This sensor has two probes through which current passes in soil, then read the resistance of soil for reading moisture level. We know that water makes the soil more prone to electric conductivity resulting in less resistance in soil where on the other hand dry soil has poor electrical conductivity thus more resistance in soil.

4.2.2. Temperature and Humidity Sensor

The DHT11 is a basic, ultra low-cost digital temperature and humidity sensor shown in Fig 3. It uses a capacitive humidity sensor and a thermostat to measure the surrounding air, and spits out a digital signal on the data pin. It measures relative humidity. Relative humidity is the amount of water vapor in air vs. the saturation point of water vapor in air. At the saturation point, water vapor starts to condense and accumulate on surfaces forming dew. It detects water vapor by measuring the electrical resistance between two electrodes.

4.2.3. Bluetooth Wireless Technology

Bluetooth is a high-speed, low-power microwave wireless link technology, designed to connect phones, laptops and other portable equipment together with little or no work by the user. Unlike infra-red, Bluetooth does not require line-of-sight positioning of connected units. The technology uses modifications of existing wireless LAN techniques but is most notable for its small size and low cost shown in Figure 2. The current prototype circuits are contained on a circuit board 0.9cm square, with a much smaller single chip version in development. The fundamental strength of Bluetooth wireless technology is the ability to simultaneously handle data and voice transmissions, which provides users with a variety of innovative solutions.



Fig 2- Bluetooth Device

This technology achieves its goal by embedding tiny, inexpensive, short-range transceivers into the electronic devices that are available today. The radio operates on the globally available unlicensed radio band, 2.45 GHz, and supports data speeds of up to 721 Kbps, as well as three voice channels. Each device has a unique 48-bit address from the IEEE 802 standard. Connections can be point-to-point or multipoint. The maximum range is 10 meters but can be extended to 100 meters by increasing the power. Bluetooth devices are protected from radio interference by changing their frequencies arbitrarily up to a maximum of 1600

times a second, a technique known as frequency hopping. Moreover, Bluetooth devices won't drain precious battery life. The Bluetooth specification targets power consumption of the device from a hold mode consuming 30 micro amps to the active transmitting range of 8-30 milliamps.

Bluetooth device uses radio waves instead of wires or cables to connect to a phone or computer. A Bluetooth product, like a headset or watch, contains a tiny computer chip with a Bluetooth radio and software that makes it easy to connect. When two Bluetooth devices want to talk to each other, they need to pair. Communication between Bluetooth devices happens over short-range, ad hoc networks known as piconets. A piconet is a network of devices connected using Bluetooth technology. When a network is established, one device takes the role of the master while all the other devices act as slaves. Piconets are established dynamically and automatically as Bluetooth devices enter and leave radio proximity. The sensors are connected to the Arduino board. These hardware communicate via Bluetooth.

V. Proposed System

Irrigation can be automated by using sensors, microcontroller, Bluetooth, and android application as shown in Fig.3. The low cost soil moisture sensor and temperature and humidity sensor are used. They continuously monitor the field. The sensors are associated to arduino board. The sensor information acquired are communicated through wireless transmission and are reached to the client so he can control irrigation. The versatile application can be planned in such a manner to analyze the information got and to check with the limit upsides of moisture, humidity and temperature. The choice can be made either by the application naturally without client interference or manually through application with client interference. On the off chance that dirt dampness is less than the limit esteem the engine is turned ON and if the soil dampness surpasses the edge esteem the engine is switched OFF.

The sensors are connected to the Arduino board. These hardware communicate through wireless Bluetooth transmission so that user can access the data through his mobile that has an android application which can get the sensor data from the arduino via Bluetooth. As far as cost of device is considered Bluetooth technology is used which can be replaced by wi-fi. motor is switched OFF.

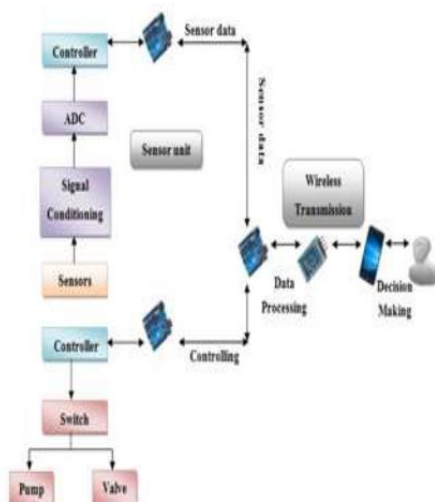


Fig.3:- System Architecture

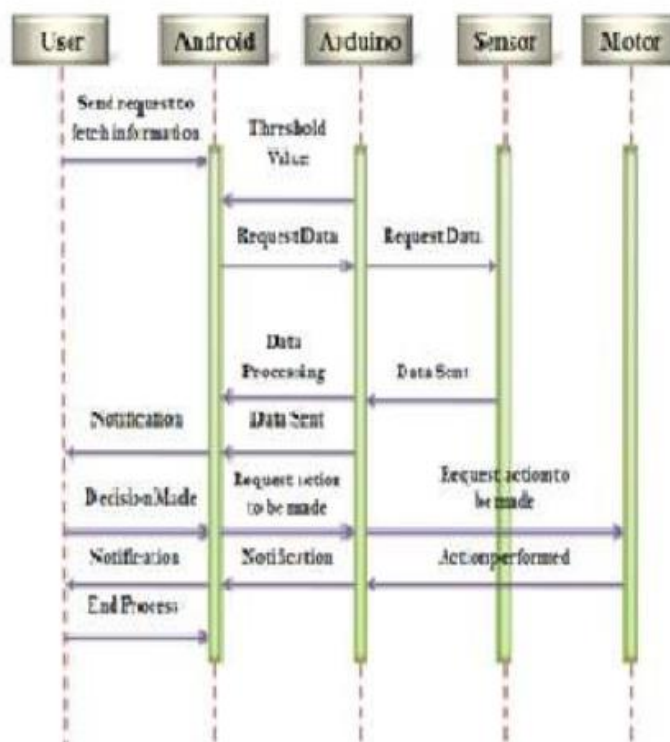


Fig.4- Sequence Diagram for the automatic irrigation

The Arduino board is programmed using Embedded C in order to control the transmission of sensor data and the working of motor according to the decision made. The coordination of the motor and 3 sensors is maintained by the program fed into the arduino. Water is supplied to 3 different areas by using Servo Motor, motor that can move its head at different angles. Using this, the head of the motor is made to move at 3 different angle so that water can be supplied at different areas where the sensors are placed. The sensors continuously send data regarding moisture content of the soil. Whichever sensor indicates low moisture content to that place motor is switched on and then water is pumped, if it indicates high moisture content pumping of water is stopped by switching of the motor. All these are managed by the program that has been written into the Arduino Microcontroller. The coordination of all the components are shown in the figure 4. The Arduino and the user communicate via Bluetooth. The range of Bluetooth technology is application specific. The threshold values for both soil moisture and temperature and humidity, will be set and stored in the arduino and mobile application. The sensor value varies according to the climatic conditions. The soil moisture will be different in summer and winter seasons and so the temperature and humidity values. The threshold value is fixed after considering all these environmental and climatic conditions. The motor will be switched on automatically if the soil moisture value falls below the threshold and vice versa. The farmer can even switch on the motor from mobile using mobile application. The

irrigation system is automated once the control received from the mobile application. Through Bluetooth the decision is sent to the arduino and accordingly the motor switches are operated. The ultrasonic sensor is used to monitor water level in reservoir. The ultrasonic sensor works based on the piezoelectric method. It has a trigger pin and an echo pin. The trigger pin acts as a transmitter and the echo pin is a reflector. The trigger pin sends ultrasonic waves once it starts functioning. The ultrasonic waves hit the water and are reflected towards the echo pin. The duration to receive the echo is calculated and that indicates the water level. The duration is converted to the distance using the following equation (1) and (2).

Distance in cm = (duration/2) / 29.1 (1)

Distance in inches = (duration/2) / 74 (2)

Before the motor is switched on, the water level is checked to ensure that the required amount of water is available for irrigation. If the required amount of water is not present, the motor will not be switched on or only a less amount of water is supplied. The notification is sent to the farmer's mobile for further decision to be made. The farmer can also be able to switch on and off the motor from the mobile application [13].

5.1 Android Mobile Application

Android is used to develop mobile applications for automatic irrigation. Android is a mobile operating system developed by Google, based on the Linux kernel and designed primarily for touch screen mobile devices such as smart phones and tablets. Android's user interface is mainly based on direct manipulation using touch gestures that loosely correspond to real-world actions, such as swiping, tapping to manipulate on-screen objects, along with a virtual keyboard for text input [13]. The sensor data and threshold value are stored in local memory of the mobile. The user can read the sensor data, and can set the system into automatic mode so that the system automatically switches motor depending on the sensor data and previously set threshold value. Also the user can set the system to manual mode and he himself can decide the switching of the motor. And he can get the notifications regarding the water level in reservoir so that he can make alternatives when there is scarcity of water in reservoir.

5.2 ADVANTAGES OF SMART AGRICULTURE USING IOT

Traditional irrigation strategies are not suitable for dealing with the shortage of irrigation water, this sector must benefit from modern technological advances. Hence the new smart agricultural irrigation system has the following advantages.

- Increase the productivity: Productivity on farmland is going to increase.
- Reduce water consumption.
- No manpower required.
- Reduce soil erosion and nutrient leaching.
- Cost effective method.
- High quality crop production.
- System not damaged by weather and birds.
- Efficient use of water.

VI. RESULT

The smart irrigation system was tested on a artificial small plot with all the above mentioned situation. The moisture value of soil moisture sensor is set to very low (i.e. 200) in IDE code of 328P microcontroller and it functioning properly. Also the condition of climate change is demonstrated well along with the power failure condition. In addition to this, the real time data of moisture sensor is displayed in graphical form on BOLT cloud page.

VII. CONCLUSION

Nowadays innovations can be consolidated to let down the cost and maximize utilization of resources. Currently, farmers control irrigation method manually and irrigate their area at a systematic period. These mechanisms diminish high amount of water and the conclusion is water loss. While dry areas have less rainfall and irrigation is challenging. The smart agricultural system guarantees higher productivity with efficient use of water. Automation of the irrigation control process by using the detected environmental parameters to be needed. Smart irrigation can be automated with the help of current technologies presented above and its main advantages are increase in productivity, reduce water consumption and reduce soil erosion.

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